

Box 2.3 DIFFERENTIALS

The “exterior derivative” or “gradient” df of a function f is a more rigorous version of the elementary concept of “differential.”

In elementary textbooks, one is presented with the differential df as representing “an infinitesimal change in the function $f(\mathcal{P})$ ” associated with some infinitesimal displacement of the point \mathcal{P} ; but one will recall that the displacement of \mathcal{P} is left arbitrary, albeit infinitesimal. Thus df represents a change in f in some unspecified direction.

But this is precisely what the exterior derivative df represents. Choose a particular, infinitesimally long displacement \mathbf{v} of the point \mathcal{P} . Let the dis-

placement vector \mathbf{v} pierce df to give the number $\langle df, \mathbf{v} \rangle = \partial_{\mathbf{v}}f$. That number is the change of f in going from the tail of \mathbf{v} to its tip. Thus df , before it has been pierced to give a number, represents the change of f in an unspecified direction. The act of piercing df with \mathbf{v} is the act of making explicit the direction in which the change is to be measured. The only failing of the textbook presentation, then, was its suggestion that df was a scalar or a number; the explicit recognition of the need for specifying a direction \mathbf{v} to reduce df to a number $\langle df, \mathbf{v} \rangle$ shows that in fact df is a 1-form, the gradient of f .

§2.8. THE CENTRIFUGE AND THE PHOTON

Vectors, metric, 1-forms, functions, gradients, directional derivatives: all these geometric objects and more are used in flat spacetime to represent physical quantities; and all the laws of physics must be expressible in terms of such geometric objects.

As an example, consider a high-precision redshift experiment that uses the Mössbauer effect (Figure 2.9). The emitter and the absorber of photons are attached to

Geometric objects in action: example of centrifuge and photon

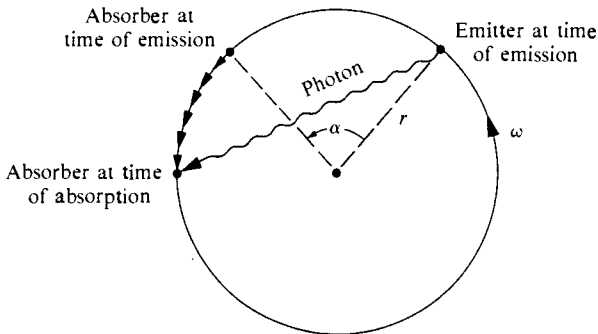


Figure 2.9.
The centrifuge and the photon.

the rim of a centrifuge at points separated by an angle α , as measured in the inertial laboratory. The emitter and absorber are at radius r as measured in the laboratory, and the centrifuge rotates with angular velocity ω . **PROBLEM:** What is the redshift measured,

$$z = (\lambda_{\text{absorbed}} - \lambda_{\text{emitted}}) / \lambda_{\text{emitted}}$$

in terms of ω , r , and α ?

SOLUTION: Let \mathbf{u}_e be the 4-velocity of the emitter at the event of emission of a given photon; let \mathbf{u}_a be the 4-velocity of the absorber at the event of absorption; and let \mathbf{p} be the 4-momentum of the photon. All three quantities are vectors defined without reference to coordinates. Equally coordinate-free are the photon energies E_e and E_a measured by emitter and absorber. No coordinates are needed to describe the fact that a specific emitter emitting a specific photon attributes to it the energy E_e ; and no coordinates are required in the geometric formula

$$E_e = -\mathbf{p} \cdot \mathbf{u}_e \quad (2.29)$$

for E_e . [That this formula works can be readily verified by recalling that, in the emitter's frame, $u_e^0 = 1$ and $u_e^j = 0$; so

$$E_e = -p_\alpha u_e^\alpha = -p_0 = +p^0$$

in accordance with the identification “(time component of 4-momentum) = (energy).”] Analogous to equation (2.29) is the purely geometric formula

$$E_a = -\mathbf{p} \cdot \mathbf{u}_a$$

for the absorbed energy.

The ratio of absorbed wavelength to emitted wavelength is the inverse of the energy ratio (since $E = h\nu = hc/\lambda$):

$$\frac{\lambda_a}{\lambda_e} = \frac{E_e}{E_a} = \frac{-\mathbf{p} \cdot \mathbf{u}_e}{-\mathbf{p} \cdot \mathbf{u}_a}.$$

This ratio is most readily calculated in the inertial laboratory frame

$$\frac{\lambda_a}{\lambda_e} = \frac{p^0 u_e^0 - p^j u_e^j}{p^0 u_a^0 - p^j u_a^j} \equiv \frac{p^0 u_e^0 - \mathbf{p} \cdot \mathbf{u}_e}{p^0 u_a^0 - \mathbf{p} \cdot \mathbf{u}_a}. \quad (2.30)$$

(Here and throughout we use boldface Latin letters for three-dimensional vectors in a given Lorentz frame; and we use the usual notation and formalism of three-dimensional, Euclidean vector analysis to manipulate them.) Because the magnitude of the ordinary velocity of the rim of the centrifuge, $v = \omega r$, is unchanging in time, u_e^0 and u_a^0 are equal, and the magnitudes—but not the directions—of \mathbf{u}_e and \mathbf{u}_a are equal:

$$u_e^0 = u_a^0 = (1 - v^2)^{-1/2}, \quad |\mathbf{u}_e| = |\mathbf{u}_a| = v/(1 - v^2)^{1/2}.$$

From the geometry of Figure 2.9, one sees that \mathbf{u}_e makes the same angle with \mathbf{p} as does \mathbf{u}_a . Consequently, $\mathbf{p} \cdot \mathbf{u}_e = \mathbf{p} \cdot \mathbf{u}_a$, and $\lambda_{\text{absorbed}}/\lambda_{\text{emitted}} = 1$. *There is no redshift!*

Notice that this solution made no reference whatsoever to Lorentz transformations—they have not even been discussed yet in this book! The power of the geometric, coordinate-free viewpoint is evident!